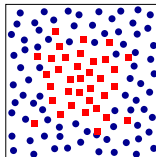
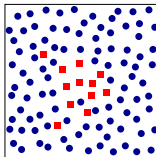
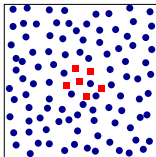
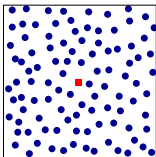


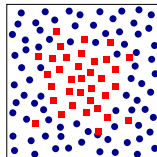
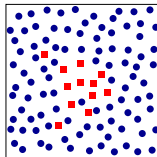
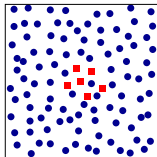
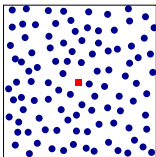
# The Fisher-KPP Equation and other Pulled Fronts

Éric Brunet

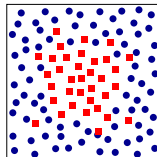
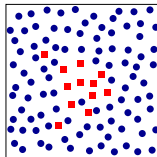
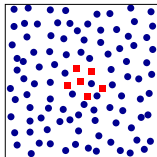
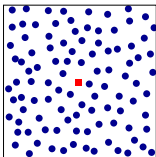
Laboratoire de Physique Statistique, É.N.S., UPMC, Paris

Banff 2010



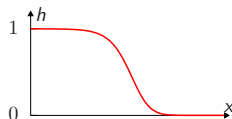


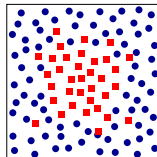
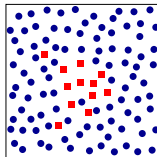
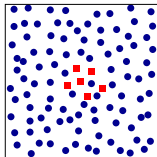
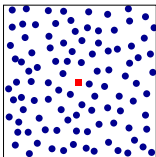
$A$  and  $B$  diffuse,  $A + B \rightarrow 2A$



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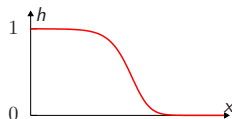
Let  $h(x, t) =$  proportion of  $A$  around  $x$  at time  $t$





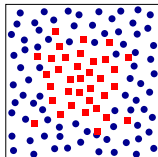
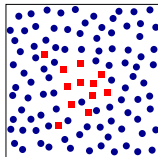
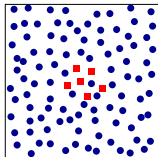
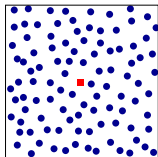
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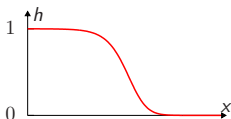
In the limit of infinite concentration:

$$\partial_t h = \partial_x^2 h + h(1 - h) \quad \text{Fisher-KPP equation}$$



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$$\partial_t h = \partial_x^2 h + h(1 - h) \quad \text{Fisher-KPP equation}$$

For large but finite concentration:

$$\partial_t h = \partial_x^2 h + h(1 - h) + (\text{small noise term}) \quad \text{Stochastic Fisher-KPP equation}$$

Before starting...

I am a physicist

There won't be any rigorous proof

but only...

Heuristics      Arguments      Ideas      Hand-waving  
Conjectures    Theories    Plausible explanations    Intuitions

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Heuristics	Arguments	Ideas	Hand-waving
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Diffusive processes

$$\partial_t \rho + \operatorname{div} \mathbf{j} = 0, \quad \mathbf{j} = -D \mathbf{grad} \rho \quad \Longrightarrow \quad \partial_t \rho = D \Delta \rho; \quad \langle x^2 \rangle = 2Dt$$



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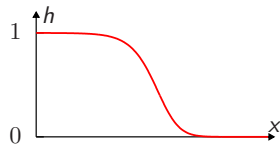
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The mathematician's convention  
 $\langle x^2 \rangle = t$

The physicist's convention  
 $D = 1$

# Outline

## 1 Deterministic Fronts



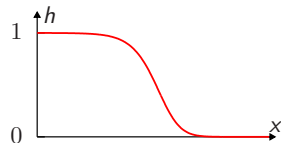
$$\partial_t h = \partial_x^2 h + h(1 - h)$$

$$h(x, t + 1) = \min \left[ 1, 2 \int_0^1 d\epsilon h(x - \epsilon, t) \right]$$

...

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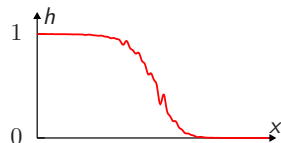


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## 2 Stochastic Fronts



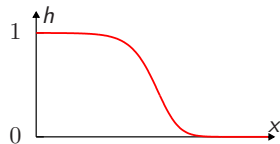
$$\partial_t h = \partial_x^2 h + h(1 - h) + (\text{small noise term})$$

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# Outline

## 1 Deterministic Fronts

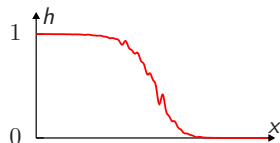


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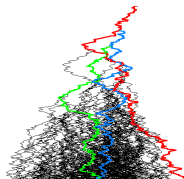


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...

## 3 Fronts and Branching Brownian Motion



# Deterministic fronts

$$\partial_t h = \partial_x^2 h + h - h^2$$

$h(x, t) = 0$  is an **unstable** solution

$h(x, t) = 1$  is an **stable** solution

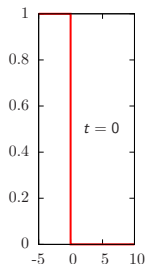
what if  $h(x, 0) = \left( \begin{array}{c} 1 \\ \text{---} \\ 0 \end{array} \right) ?$

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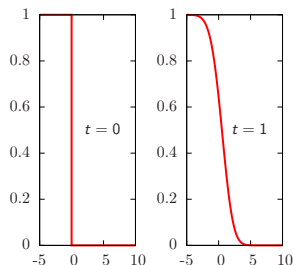
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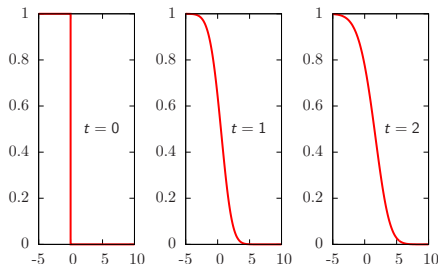
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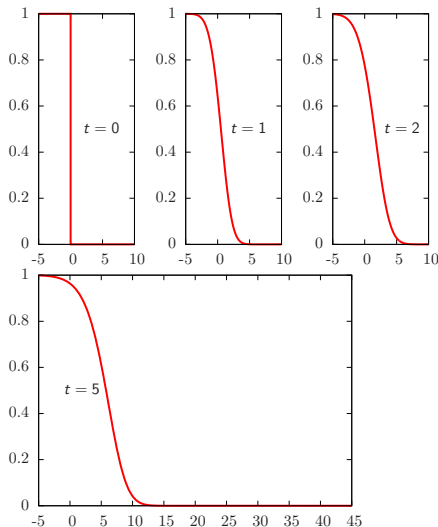
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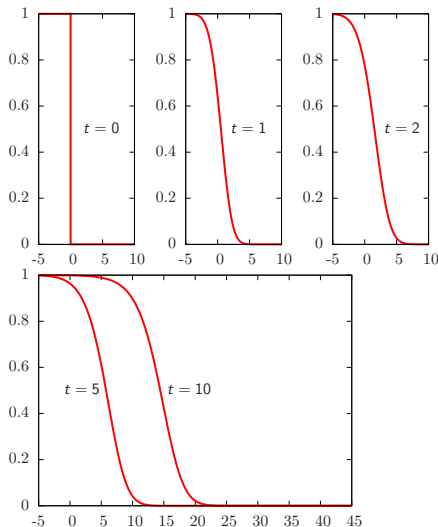
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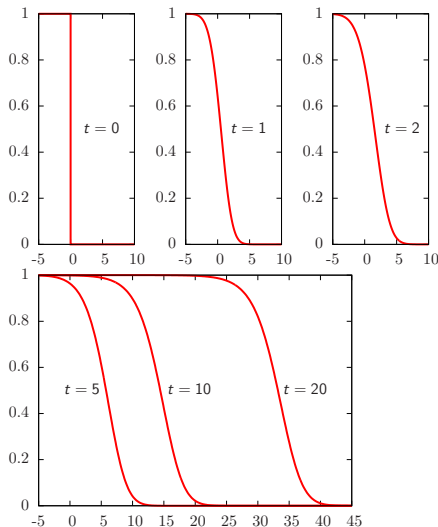
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## Questions

$$\text{If } h(x, 0) = \left( \begin{array}{c} 1 \\ \phantom{1} \\ 0 \end{array} \right),$$

$$h(X_t + z, t) \xrightarrow[t \rightarrow \infty]{} f_2(z)$$

with

$$X_t = (\text{position of the front})$$

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$$f_2(z) = \left( \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} \right) = \text{(final shape of the front)}$$

What is  $X_t$ ? What is  $f_2(z)$ ?

Answer:

$$X_t = 2t - \frac{3}{2} \ln t + a_0 - \frac{3\sqrt{\pi}}{\sqrt{t}} + \frac{a_1}{t} + \frac{a_{3/2}}{t^{3/2}} + \dots \quad \text{for large } t$$

## Questions

$$\text{If } h(x, 0) = \left( \begin{array}{c} 1 \\ \text{---} \\ 0 \end{array} \right),$$

$$\text{or if } h(x, 0) = \left( \begin{array}{c} 1 \\ \text{---} \end{array} \right)$$

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## Many equations, same kind of behavior

$$\partial_t h = \partial_x^2 h + h - h^2, \quad X_t = 2t - \frac{3}{2} \ln t + a_0 - \frac{3\sqrt{\pi}}{\sqrt{t}} + \frac{a_1}{t} + \dots$$

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$$h(x, t + \epsilon) = h(x, t) + \epsilon \left[ \frac{h(x + s, t) + h(x - s, t) - 2h(x, t)}{s^2} + h - h^2 \right]$$

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### Fronts propagating into an unstable state

$h = 0$  and  $h = 1$  are solutions

$h = 0$  is unstable (growth term),  $h = 1$  is stable (saturation term)

First order equation in time, some mixing (diffusion) in space

## Many velocities

$$\partial_t h = \partial_x^2 h + h - h^2$$

Uniformly translating front such that  $h(x, t) = f_v(x - vt)$

$$\partial_z^2 f_v + v \partial_z f_v + f_v - f_v^2 = 0$$

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Look in the unstable region, where  $f_v(z) \ll 1$   
Linear equation

$$f_v \approx e^{-\gamma z} \quad [\text{or } h \approx e^{-\gamma(x-vt)}]$$

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$$f_v \approx e^{-\gamma z} \quad [\text{or } h \approx e^{-\gamma(x-vt)}]$$

... is solution if

$$\gamma^2 f_v - \gamma v f_v + f_v = 0$$

# Many velocities

$$\partial_t h = \partial_x^2 h + h - h^2$$

Uniformly translating front such that  $h(x, t) = f_v(x - vt)$

$$\partial_z^2 f_v + v \partial_z f_v + f_v - f_v^2 = 0$$

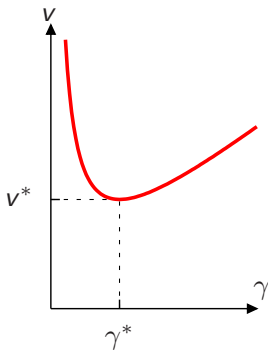
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$$v = \underbrace{\gamma + \frac{1}{\gamma}}_{v(\gamma)}$$



# Many velocities

$$h(x, t) = f_v(x - vt) \ll 1, \text{ linear equation, } f_v(z) \approx e^{-\gamma z} \text{ or } h \approx e^{-\gamma(x-vt)}$$
$$\partial_t h = \partial_x^2 h + h - h^2 \implies \gamma v h = \gamma^2 h + h \implies v(\gamma) = \gamma + \frac{1}{\gamma}$$

$$h(x, t+1) = \min \left[ 1, 2 \int_0^1 d\epsilon h(x - \epsilon, t) \right] \implies e^{\gamma v} h = 2 \int_0^1 d\epsilon e^{\gamma \epsilon} h \implies v(\gamma) = \frac{1}{\gamma} \ln \left[ 2 \int_0^1 d\epsilon e^{\gamma \epsilon} \right]$$

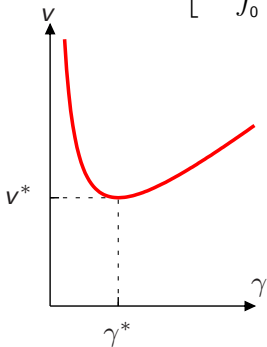


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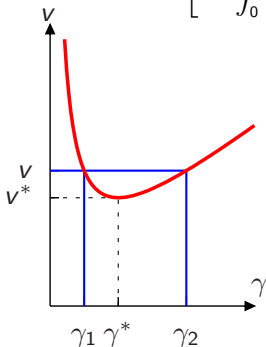


# Many velocities

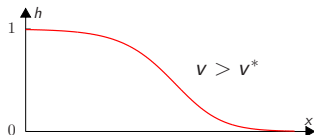
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$$f_v \approx A_1 e^{-\gamma_1 z} + A_2 e^{-\gamma_2 z}$$

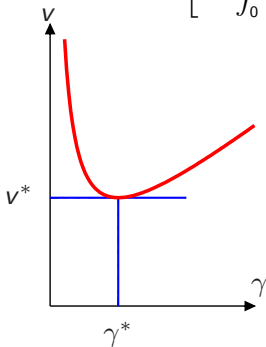


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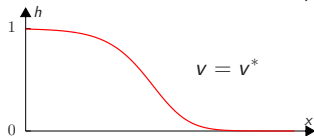
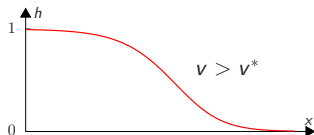
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$$f_v \approx A_1 e^{-\gamma_1 z} + A_2 e^{-\gamma_2 z}$$

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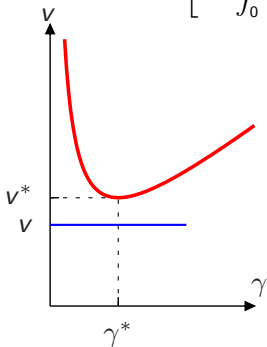


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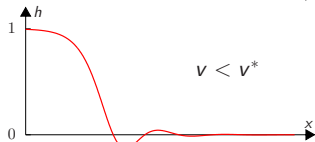
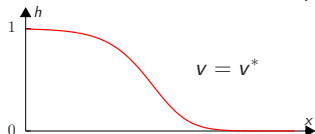
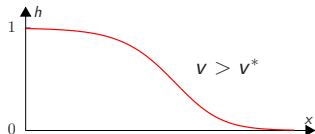
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$$f_v \approx A \sin(\gamma_I z + \phi) e^{-\gamma_R z}$$

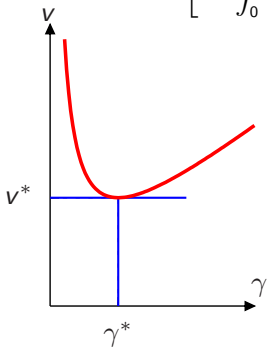


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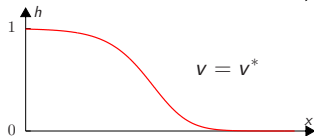
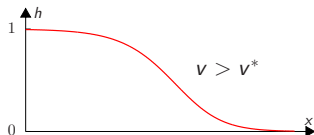
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Fronts with  $v < v^*$  are unstable

## Linear perturbation

$$\partial_t h = \partial_x^2 h + h - \cancel{h^2}, \quad h(x, 0) = \begin{pmatrix} 1 \\ \text{---} \underset{0}{\text{---}} \text{---} 0 \end{pmatrix}$$

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At a position  $x = vt + y$

$$h(vt + y, t) = \frac{\epsilon}{\sqrt{4\pi t}} \exp \left[ \left(1 - \frac{v^2}{4}\right)t - \frac{vy}{2} - \frac{y^2}{4t} \right]$$



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A linear perturbation moves  
at velocity  $v = v^*$  ( $= 2$ )

$$h(2t + y, t) = \frac{\epsilon}{\sqrt{4\pi t}} \exp \left[ -y - \frac{y^2}{4t} \right]$$

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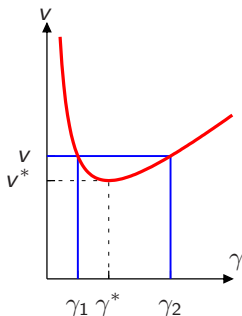
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## Shape and velocity

$$\partial_t h = \partial_x^2 h + h - h^2,$$

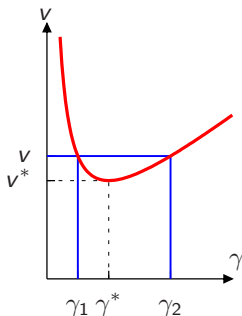
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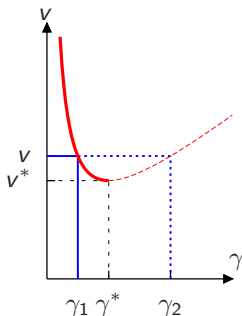
For  $v > v^*$ ,  $f_v \approx A_1 e^{-\gamma_1 z} + A_2 e^{-\gamma_2 z} +$   
 $A_{11} e^{-2\gamma_1 z} + A_{12} e^{-(\gamma_1 + \gamma_2)z} + A_{22} e^{-2\gamma_2 z} + \dots$



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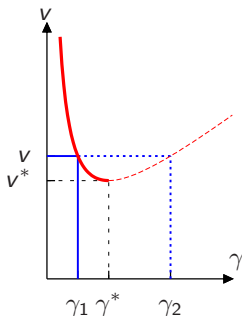


## Shape and velocity

$$\partial_t h = \partial_x^2 h + h - h^2,$$

For  $v > v^*$ ,  $f_v \approx A_1 e^{-\gamma_1 z} + \dots$

A fast front decays slowly in space  
A slow front decays quickly in space

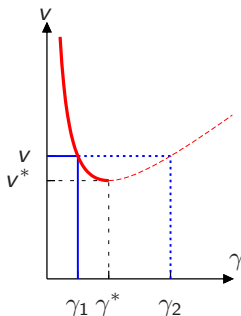
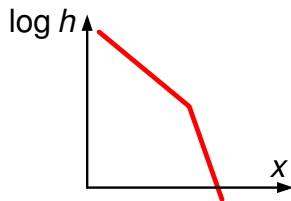


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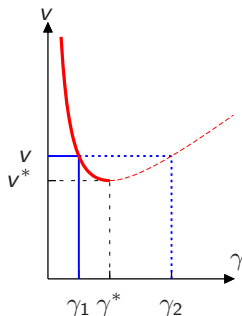
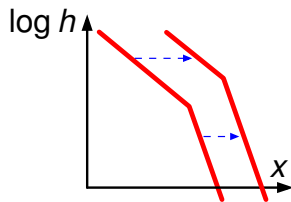


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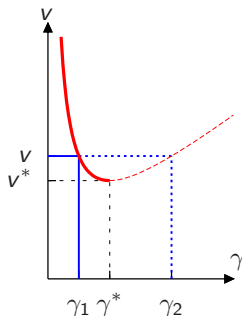
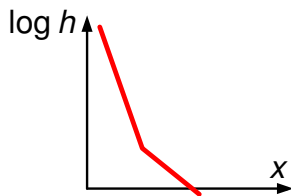
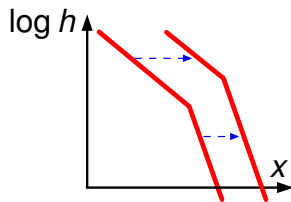


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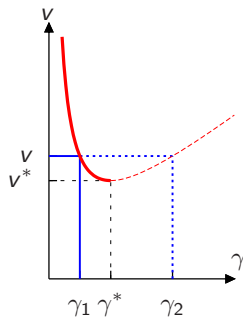
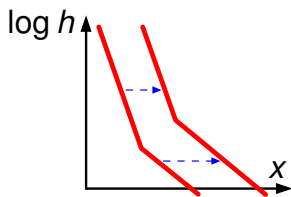
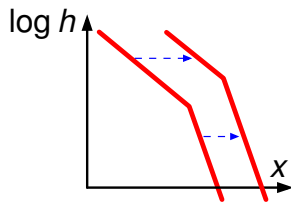


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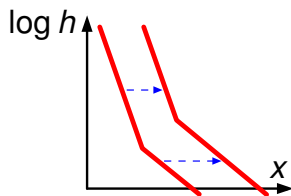
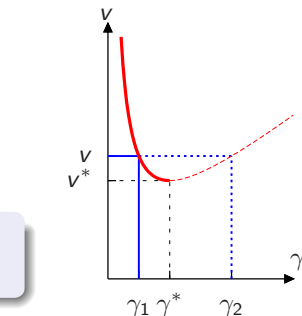
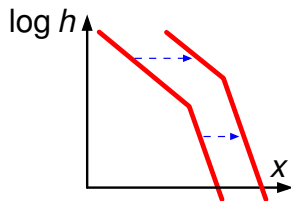


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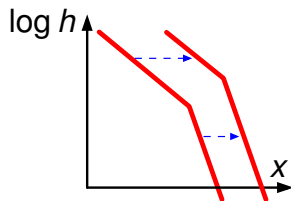
What is ahead wins

# Shape and velocity

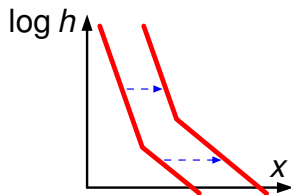
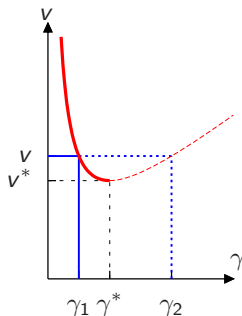
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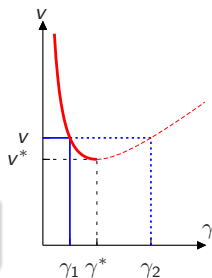
If  $h(x, 0) \sim e^{-\gamma x}$  with  $\gamma \leq \gamma^*$ , then  $v = v(\gamma)$   
If  $h(x, 0) \ll e^{-\gamma^* x}$  then  $v = v^*$ .

## When it does not work — pushed fronts

For  $v > v^*$  and  $z$  large

$$\begin{aligned}f_v &\approx A_1 e^{-\gamma_1 z} + A_2 e^{-\gamma_2 z} + A_{11} e^{-2\gamma_1 z} + \dots \\ &\approx A_1 e^{-\gamma_1 z}\end{aligned}$$

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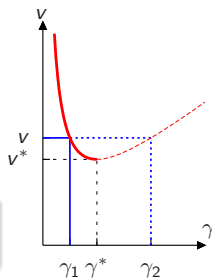


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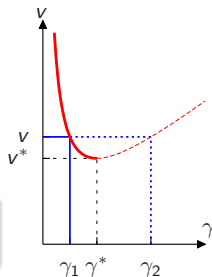
What if  $A_1 < 0$  ?

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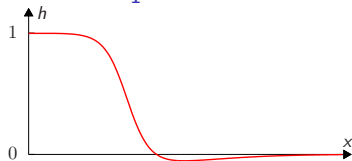
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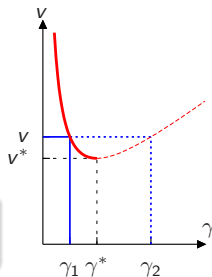


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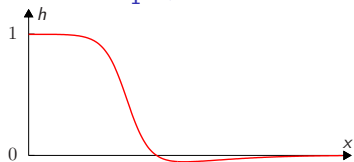
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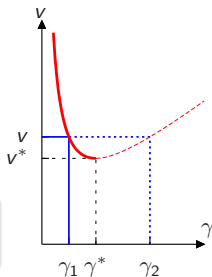
$A_1$  depends on  $v$

# When it does not work — pushed fronts

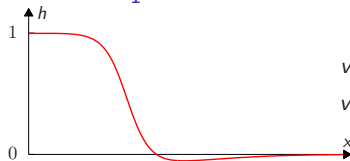
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$$\begin{aligned}f_v &\approx A_1 e^{-\gamma_1 z} + A_2 e^{-\gamma_2 z} + A_{11} e^{-2\gamma_1 z} + \dots \\ &\approx A_1 e^{-\gamma_1 z}\end{aligned}$$

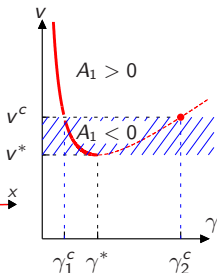
A fast front decays slowly in space  
A slow front decays quickly in space



What if  $A_1 < 0$  ?



$A_1$  depends on  $v$

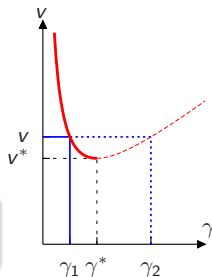


# When it does not work — pushed fronts

For  $v > v^*$  and  $z$  large

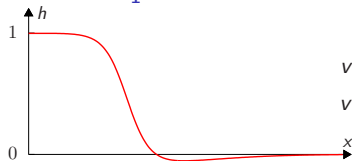
$$f_v \approx A_1 e^{-\gamma_1 z} + A_2 e^{-\gamma_2 z} + A_{11} e^{-2\gamma_1 z} + \dots$$

$$\approx A_1 e^{-\gamma_1 z}$$

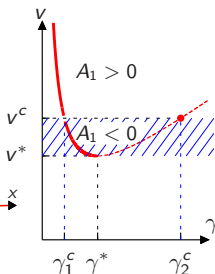


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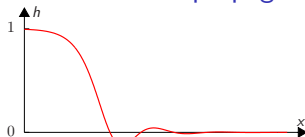


$$v = v(\gamma) \text{ if } \begin{cases} h(x, 0) \sim e^{-\gamma x} \\ \text{with } \gamma \leq \gamma_1^c \end{cases}$$

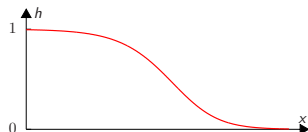
$$v = v^c \text{ if } h(x, 0) \ll e^{-\gamma_1^c x}$$

# Summary

## Pulled fronts propagating into an unstable state

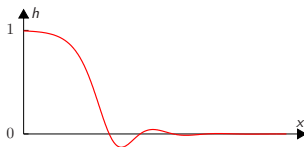


$v < v^*$ , unstable

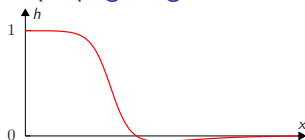


$v \geq v^*$ , stable

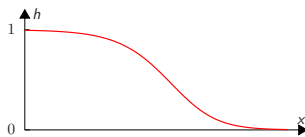
## Pushed fronts propagating into an unstable state



$v < v^*$ , unstable



$v^* \leq v < v^c$ , unstable



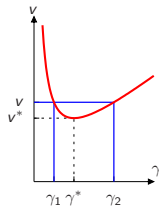
$v \geq v^c$ , stable

An initial condition decaying fast enough leads to the slowest stable front  
A pulled front goes at the same speed as a linear perturbation  
A pushed front goes faster than a linear perturbation  
A front can be pushed only if the non-linearities increase the growth rate

## An example

$$\partial_t h = \partial_x^2 h + (h - h^2)(1 + \alpha h)$$

$h = 0$  unstable,  $h = 1$  stable,  $v(\gamma) = \gamma + \frac{1}{\gamma}$ ,  $\gamma^* = 1$  and  $v^* = 2$



## An example

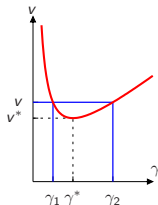
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We look for uniformly translating solutions

$$h(x, t) = f_v(x - vt)$$

The solution is known for *one* value of  $v$ :



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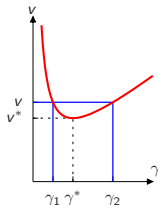
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For  $\gamma = \sqrt{\frac{\alpha}{2}}$  and  $v = \gamma + \frac{1}{\gamma}$

$$f_v(z) = \frac{1}{2} \left[ 1 - \tanh \frac{\gamma z}{2} \right]$$



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$h = 0$  unstable,  $h = 1$  stable,  $v(\gamma) = \gamma + \frac{1}{\gamma}$ ,  $\gamma^* = 1$  and  $v^* = 2$

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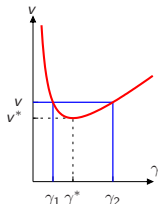
For $\gamma = \sqrt{\frac{\alpha}{2}}$ and $v = \gamma + \frac{1}{\gamma}$	$f_v(z) = \frac{1}{2} \left[ 1 - \tanh \frac{\gamma z}{2} \right]$
--	--

But

$$f_v(z) = e^{-\gamma z} - e^{-2\gamma z} + e^{-3\gamma z} - \dots$$

instead of

$$f_v(z) = A_1 e^{-\gamma_1 z} + A_2 e^{-\gamma_2 z} + \dots$$





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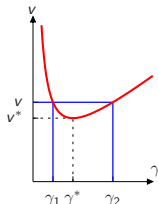
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Either  $\gamma_1$  or  $\gamma_2$  is missing ( $A_1 = 0$  or  $A_2 = 0$ )



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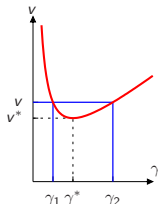
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Either  $\gamma_1$  or  $\gamma_2$  is missing ( $A_1 = 0$  or  $A_2 = 0$ )

If  $\alpha > 2$ , then  $\gamma = \gamma_2$ , and  $A_1 = 0$ , and the front is pushed with

$$v_c = \sqrt{\frac{\alpha}{2}} + \sqrt{\frac{2}{\alpha}}$$



## Bramson's result

For  $h(x, 0) = \left( \begin{array}{c} 1 \\ \text{---} \\ 0 \end{array} \right)$ ,  $\frac{X_t}{t} \rightarrow v^*$  and  $h(X_t + z, t) \xrightarrow{t \rightarrow \infty} f_{v^*}(z)$

with

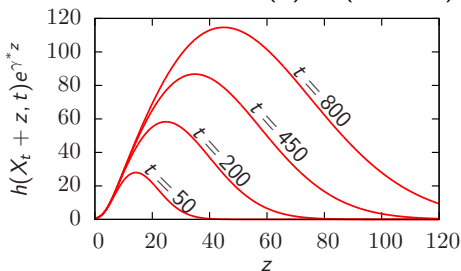
$$f_{v^*}(z) \approx (Az + B)e^{-\gamma^* z} \quad \text{for large } z$$

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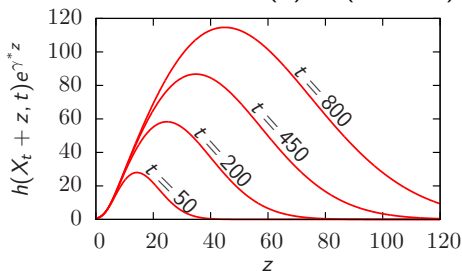


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$$h(X_t + z) \approx \sqrt{t} S\left(\frac{z}{\sqrt{t}}\right) e^{-\gamma^* z}$$

$$S(u) \approx u \text{ for small } u \ (z \ll \sqrt{t})$$

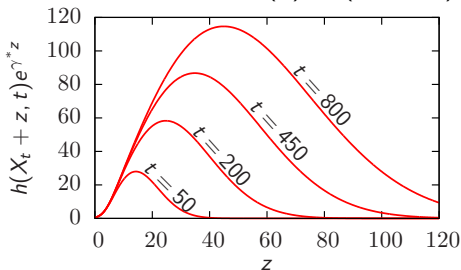
$S(u)$  decays fast for large  $u$  ( $t \ll z^2$ )

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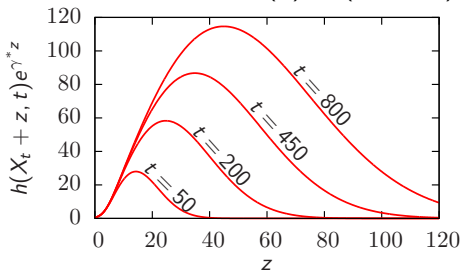
$$S(u) = ue^{-\frac{u^2}{4\cdots}} \text{ and } X_t = v^* t - \frac{3}{2\gamma^*} \ln t + \cdots$$

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Solution of the linearized equation  $\partial_t h = \partial_x^2 h + h$

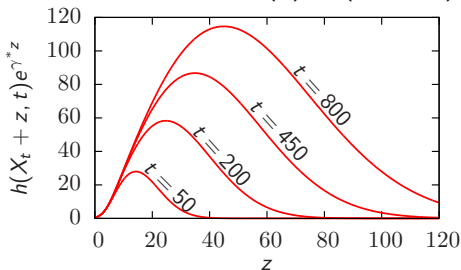
$$h(2t + y, t) = \left\{ \frac{1}{\sqrt{4\pi t}} e^{-y - \frac{y^2}{4t}}, \right.$$

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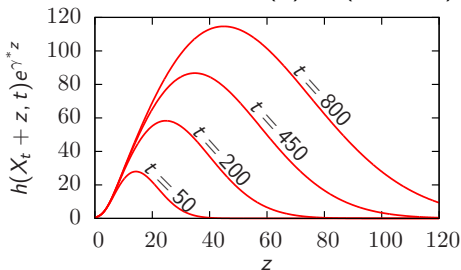


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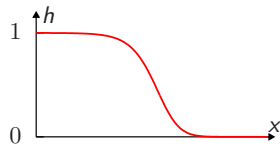
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# Outline

## 1 Deterministic Fronts

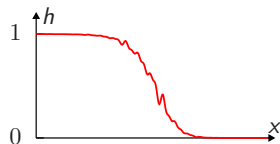


$$\partial_t h = \partial_x^2 h + h(1-h)$$

$$h(x, t+1) = \min \left[ 1, 2 \int_0^1 d\epsilon h(x-\epsilon, t) \right]$$

...

## 2 Stochastic Fronts

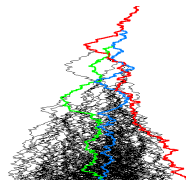


$$\partial_t h = \partial_x^2 h + h(1-h) + (\text{small noise term})$$

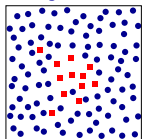
$$h(x, t+1) = \min \left[ 1, 2 \int_0^1 d\epsilon h(x-\epsilon, t) + \dots \right]$$

...

## 3 Fronts and Branching Brownian Motion



## Why the noise ?

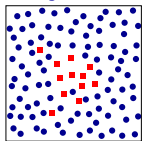


$A$  and  $B$  diffuse,  $A + B \rightarrow 2A$

Let  $h(x, t) =$  proportion of  $A$ . In the limit of infinite concentration;  $\partial_t h = \partial_x^2 h + h(1 - h)$

What to write for a finite concentration ?

## Why the noise ?



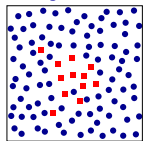
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$N$  particles on one site,  $n_t =$  number of  $A$ , and  $N - n_t =$  number of  $B$

## Why the noise ?



$A$  and  $B$  diffuse,  $A + B \rightarrow 2A$  with rate  $1/N$

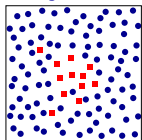
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Assuming  $n_t$  given, 
$$n_{t+dt} = \begin{cases} n_t + 1 & \text{with probability } \frac{dt}{N} n_t (N - n_t) \\ n_t & \text{with probability } 1 - \frac{dt}{N} n_t (N - n_t) \end{cases}$$

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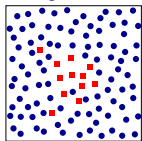
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$$\langle n_{t+dt} \rangle = n_t + \frac{dt}{N} n_t (N - n_t), \quad \text{Variance}(n_{t+dt}) = \frac{dt}{N} n_t (N - n_t)$$

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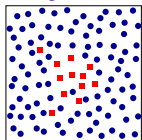
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$$n_{t+dt} = n_t + \frac{dt}{N} n_t (N - n_t) + R_t \sqrt{\frac{dt}{N} n_t (N - n_t)} \quad \text{with } \langle R_t \rangle = 0 \text{ and } \langle R_t^2 \rangle = 1$$

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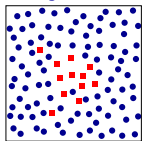
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$$\partial_t n_t = \frac{n_t(N-n_t)}{N} + \eta_t \sqrt{\frac{n_t(N-n_t)}{N}} \quad \text{with } \langle \eta_t \eta_{t'} \rangle = \delta(t - t')$$



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$A$  and  $B$  diffuse,  $A + B \rightarrow 2A$  with rate  $1/N$

Let  $h(x, t) =$  proportion of  $A$ . In the limit of infinite concentration;  $\partial_t h = \partial_x^2 h + h(1 - h)$

What to write for a finite concentration ?

$N$  particles on one site,  $n_t =$  number of  $A$ , and  $N - n_t =$  number of  $B$

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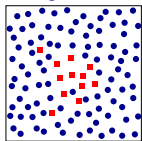
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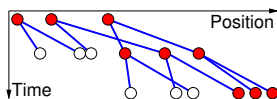
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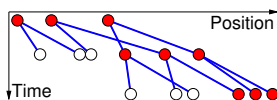
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$N (= 3)$  particles, at each time step a particle at  $x$  gives two offspring at positions  $x + \epsilon_{1,2}$  with  $\epsilon \in [0, 1]$  random. Keep only the  $N$  rightmost.



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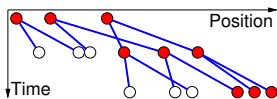


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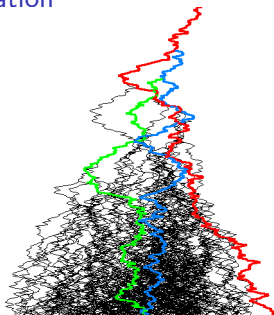
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### Branching Brownian Motion plus saturation

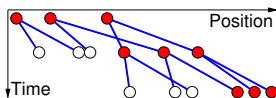
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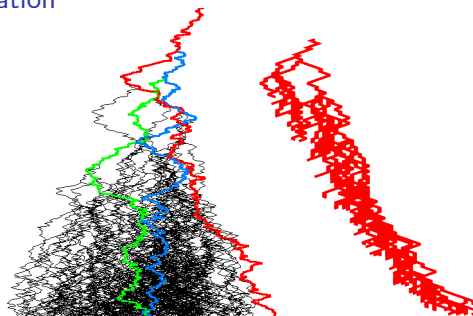


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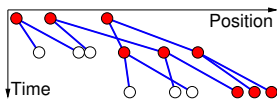
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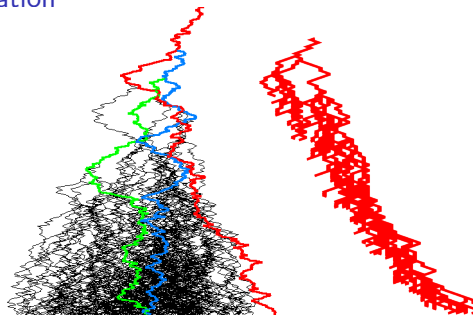


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- Particles do a Brownian motion
  - With rate 1, they split
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- When a  $(N + 1)^{\text{th}}$  particle appears, remove the leftmost to keep only  $N$
  - Or two particles crossing have a  $1/N$  chance of coalescing



# The noise term

$$\text{growth term} \approx h \qquad \text{noise term} \approx \sqrt{\frac{h}{N}}$$

$$\partial_t h = \partial_x^2 h + h(1-h) + \eta \sqrt{\frac{h(1-h)}{N}} \quad \text{with} \quad \begin{cases} \langle \eta_{x,t} \rangle = 0 \\ \langle \eta_{x,t} \eta_{x',t'} \rangle = \delta(t-t') \delta(x-x') \end{cases}$$



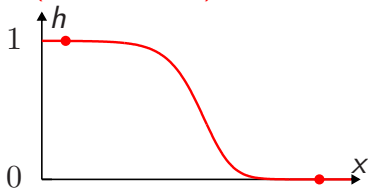
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The front (almost surely) reaches 0 and 1



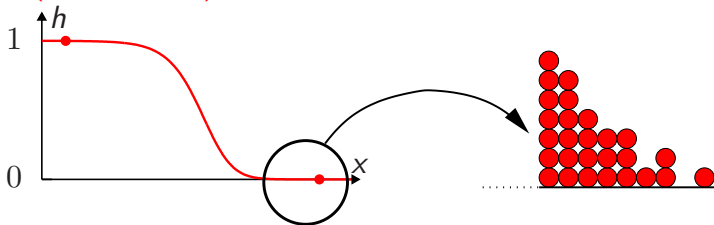
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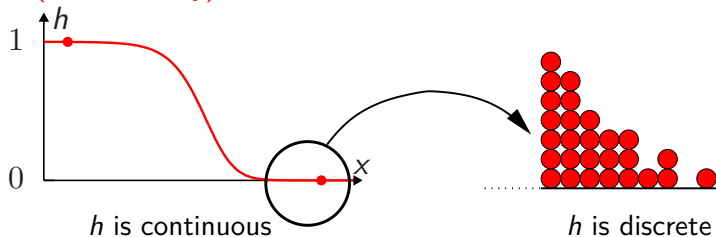
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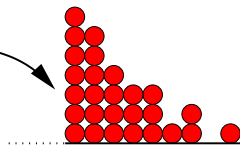
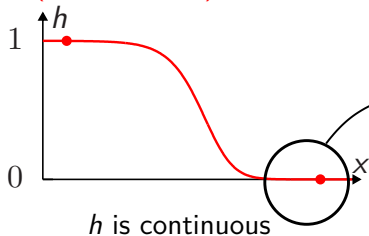
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$h$  is discrete

$Nh \simeq$  number of particles

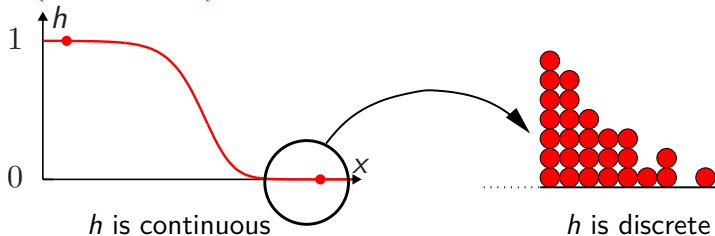
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For  $\partial_t h = h + \eta_t \sqrt{\frac{h}{N}}$ , if  $h(0) < 1/N$ ,  
then, probably,  $h(t) \rightarrow 0$

$Nh \simeq$  number of particles  
if  $h \neq 0$ , then  $h \geq 1/N$

## The cutoff approximation

$$\begin{cases} \partial_t h = \partial_x^2 h + h - h^2 + \eta_{x,t} \sqrt{\frac{1}{N}(h - h^2)} \\ \text{Wherever } h \text{ is of order } \frac{1}{N}, \text{ it should go quickly to zero} \end{cases}$$

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Other example in the discrete

$$h(x, t+1) = \min \left[ 1, 2 \int_0^1 dy h(x-y, t) + \text{noise} \right]$$

replaced by

$$h(x, t+1) = \begin{cases} 2 \int_0^1 dy h(x-y, t) & \text{if that number is between } \frac{1}{N} \text{ and } 1 \\ 1 & \text{if the number above is larger than } 1 \\ 0 & \text{if the number above is smaller than } \frac{1}{N} \end{cases}$$



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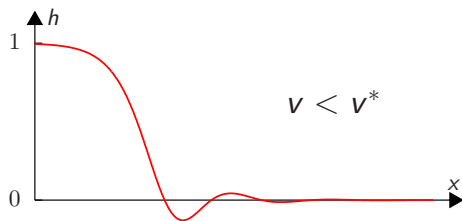
It looks likely that  $v_N^{\text{noise}} \approx v_N^{\text{cutoff}}$

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$$\left\{ \begin{array}{l} v_N^{\text{cutoff}} \leq v^* \\ \text{The shape of the front should "reach" } h = 0 \end{array} \right.$$

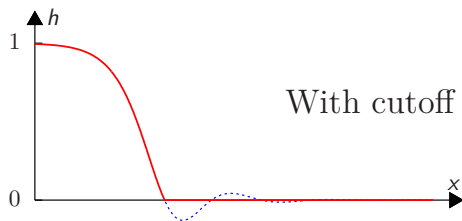
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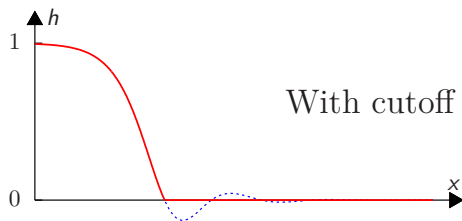
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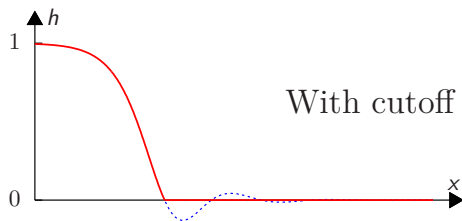


$$\gamma = \gamma_R + i\gamma_I \quad v = v(\gamma) \text{ (real)}$$

$$f_v(z) = C \sin(\gamma_I z + \phi) e^{-\gamma_R z}$$

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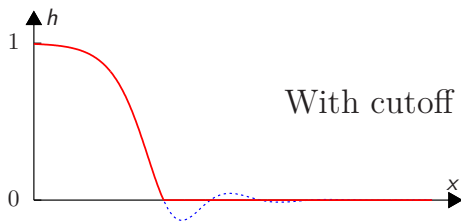


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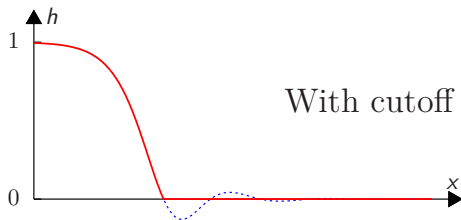
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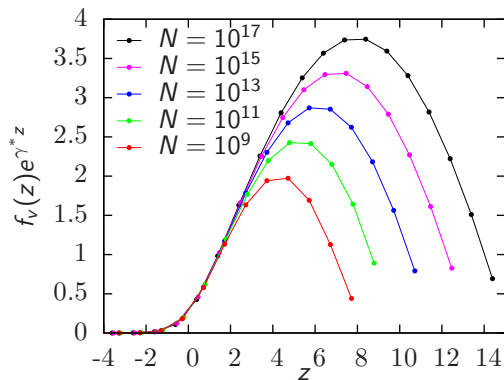
$$\gamma_I \ll 1 \implies \gamma_R \approx \gamma^* \text{ to have } v(\gamma) \text{ real}$$

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$$v_N^{\text{cutoff}} = v(\gamma) = v\left(\gamma^* + i\frac{\pi}{L}\right) = v^* - \frac{\pi^2 v''(\gamma^*)}{2L^2}$$

# Beyond the cutoff approximation

Cutoff:

$$f_v(z) \approx \text{Cste} \ln N \sin\left(\frac{\pi \gamma^* z}{\ln N}\right) e^{-\gamma^* z} \quad \text{and} \quad v_N^{\text{cutoff}} = v^* - \frac{a}{\ln^2 N} + \mathcal{O}\left(\frac{1}{\ln^3 N}\right)$$

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Position of the front fluctuates:

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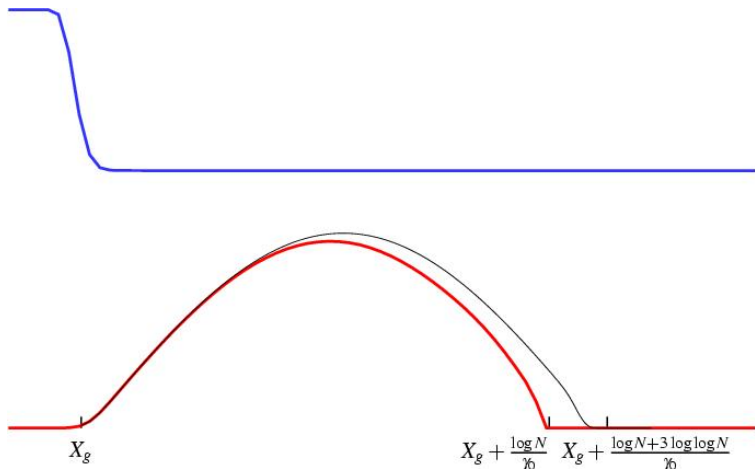
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with

$$a = \frac{\pi^2 \gamma^{*2} v''(\gamma^*)}{2} \quad b = \frac{\pi^4 \gamma^* v''(\gamma^*)}{3}$$

# Watching the fluctuations



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- $\delta$  be the size of a fluctuation
- $p(\delta)$  the probability per unit time of observing a fluctuation of size  $\delta$
- $R(\delta)$  the long term effect on the position of the front of a fluctuation

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- $p(\delta)$  the probability per unit time of observing a fluctuation of size  $\delta$
- $R(\delta)$  the long term effect on the position of the front of a fluctuation

Then, with (time to relax)  $\ll \Delta t \ll$  (time between two fluctuations)

$$X_{t+\Delta t} = X_t + v_N^{\text{cutoff}} \Delta t + \begin{cases} R(\delta) & \text{proba. } \Delta t p(\delta) d\delta \\ 0 & \text{proba. } 1 - \Delta t \int p(\delta) d\delta \end{cases}$$

# Main scenario

- A **Sine shape**. Cutoff approximation mostly correct
- Dynamics dominated by **rare and large fluctuations**
- Fluctuations relax almost **deterministically**
- A fluctuation relaxes before another occurs

Let...

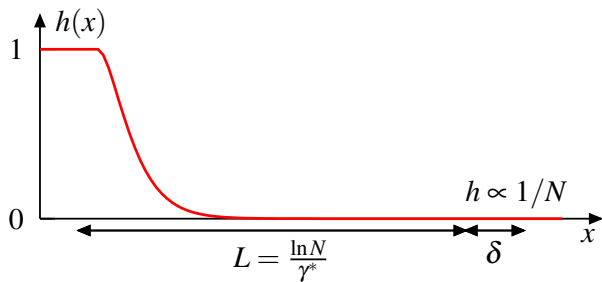
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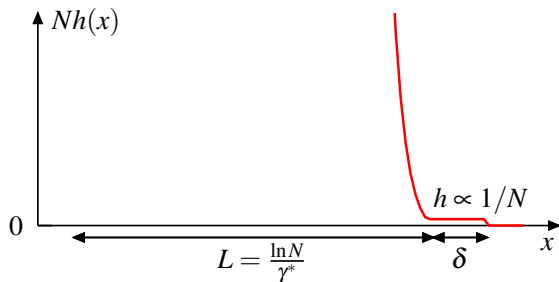
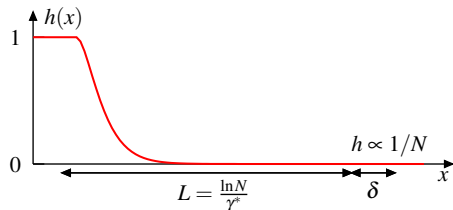
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$$v_N^{\text{noise}} = v_N^{\text{cutoff}} + \int d\delta p(\delta) R(\delta), \quad D_N^{\text{noise}} = \int d\delta p(\delta) R(\delta)^2$$

# What does a fluctuation look like ?

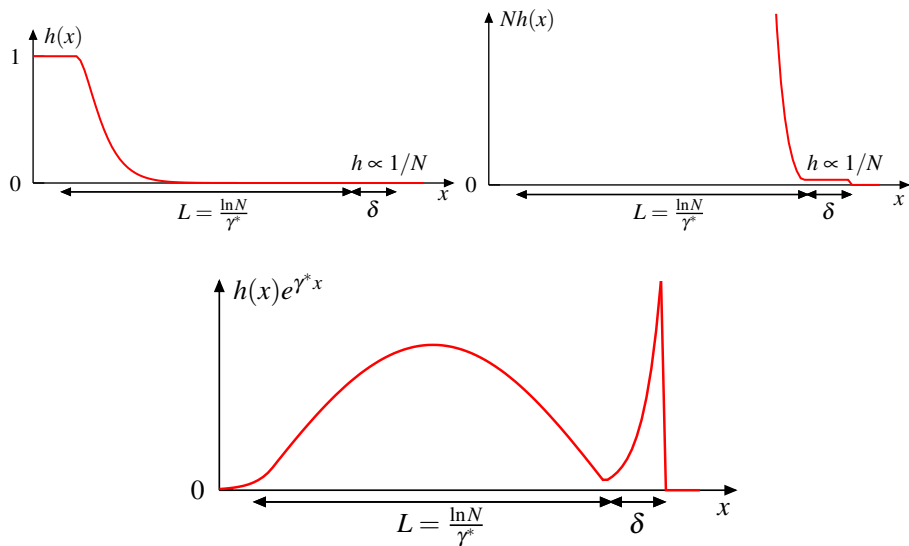


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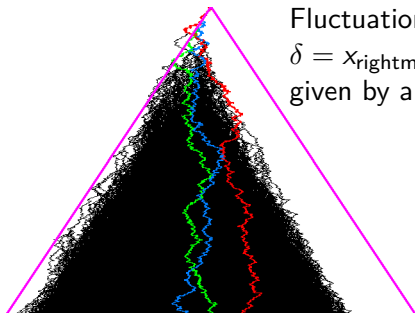
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- Fluctuations build up quickly

⇒ We can ignore saturation rule

$A$  diffuse,  $A \rightarrow 2A$ , ~~saturation rule~~

## Branching Brownian Motion

Fluctuations of  
 $\delta = x_{\text{rightmost}}$  – (position of the tip of the BBM)  
given by a Gumbel

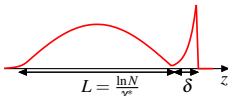


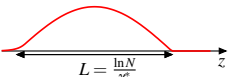
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$$h(X_t + z, t) \xrightarrow{t \rightarrow \infty} \text{[Graph]} \times e^{-\gamma^* z}$$


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$$h(X_0 + z, 0) = \text{[Graph of a red curve with a peak and a sharp spike at } z = \delta \text{]} \times e^{-\gamma^* z}$$

The graph shows a red curve on a horizontal axis labeled  $z$ . The curve starts at the origin, rises to a broad peak, then descends to a local minimum at  $z = \delta$ , where it has a very sharp spike. A horizontal double-headed arrow below the curve indicates a length  $L = \frac{\ln N}{\gamma^*}$  from the origin to the spike.

$$h(X_t + z, t) \xrightarrow{t \rightarrow \infty} \text{[Graph of a smooth red curve]} \times e^{-\gamma^* z}$$

The graph shows a smooth red curve on a horizontal axis labeled  $z$ . A horizontal double-headed arrow below the curve indicates a length  $L = \frac{\ln N}{\gamma^*}$  from the origin to the right edge of the curve.

$$h(X_t + z, t) = LG \left( \frac{z}{L}, \frac{t}{L^2} \right) e^{-\gamma^*(z + X_t - X_0 - v_{\text{cutoff}} t)}$$



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$$h(X_t + z, t) \xrightarrow{t \rightarrow \infty} \text{[Graph: A red curve that is smooth and decays to zero at the end. A horizontal arrow below the curve indicates a length } L = \frac{\ln N}{\gamma^*} \text{.]} \times e^{-\gamma^* z} = LG \left( \frac{z}{L}, \infty \right) e^{-\gamma^* R(\delta)} e^{-\gamma^* z}$$

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$$G(y, 0) = \sin(\pi y) + \text{perturbation of width } \propto \frac{1}{L} \text{ and height } \propto \frac{e^{\gamma^* \delta}}{L}$$

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## Timescales

- Relevant values of  $\delta$  are  $\approx \frac{1}{\gamma^*} 3 \ln \ln N$
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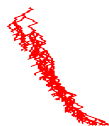
- Cutoff theory gives  $v = v^* - \frac{\pi^2 v''(\gamma^*)}{2L^2}$  with  $L = \frac{1}{\gamma^*} \ln N$
- Use instead the effective length  $L = \frac{1}{\gamma^*} [\ln N + 3 \ln \ln N]$

## Relation between $N$ and $L$

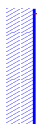
$A$  diffuse,  $A \rightarrow 2A$ , ~~keep only the  $N$  rightmost~~

## Relation between $N$ and $L$

A diffuse,  $A \rightarrow 2A$ , a wall moving at velocity  $v$  absorbs the particles



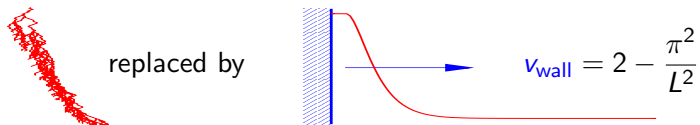
replaced by



$$v_{\text{wall}} = 2 - \frac{\pi^2}{L^2}$$

## Relation between $N$ and $L$

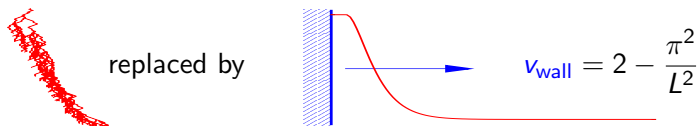
A diffuse,  $A \rightarrow 2A$ , a wall moving at velocity  $v$  absorbs the particles



- Start with one particle at  $x > 0$
- **Condition** on the fact that there is one living particle at large time  $T$
- How many particles at an intermediate time ?

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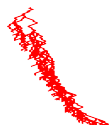


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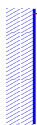
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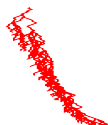
- Starts with a density looking like the actual front

$$h(x, 0) \propto L \sin \frac{\pi x}{L} e^{-x}$$

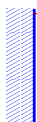
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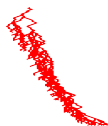
$$h(x, 0) \propto L \sin \frac{\pi x}{L} e^{-x}$$

- Populate with  $N$  particles

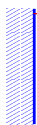
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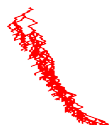
- Populate with  $N$  particles
- Proba to survive

$$L \approx \ln N + 3 \ln \ln N$$

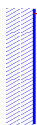


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- Starts with a density looking like the actual front

$$h(x, 0) \propto L \sin \frac{\pi x}{L} e^{-x}$$

- Populate with  $N$  particles
- Proba to survive  $\sim 1 - e^{-KNL^3 e^{-L}}$

$$L \approx \ln N + 3 \ln \ln N$$

# Conclusion

$$v_N^{\text{noise}} = v^* - \frac{\pi^2 \gamma^{*2} v''(\gamma^*)}{2(\ln N + 3 \ln \ln N + \dots)^2}$$

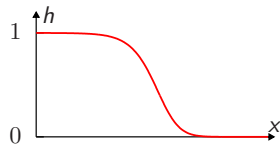
$$D_N^{\text{noise}} = \frac{\pi^4 \gamma^* v''(\gamma^*)}{3(\ln N + \dots)^3}$$

- A phenomenological theory gives a prediction for  $v_N$  and  $D_N$
- Agrees with simulations
- We still need a clean derivation

▶ Exponential model

# Outline

## 1 Deterministic Fronts

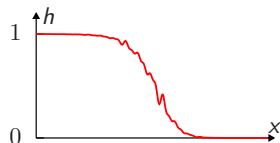


$$\partial_t h = \partial_x^2 h + h(1-h)$$

$$h(x, t+1) = \min \left[ 1, 2 \int_0^1 d\epsilon h(x-\epsilon, t) \right]$$

...

## 2 Stochastic Fronts

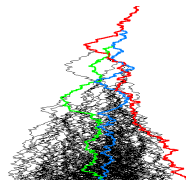


$$\partial_t h = \partial_x^2 h + h(1-h) + (\text{small noise term})$$

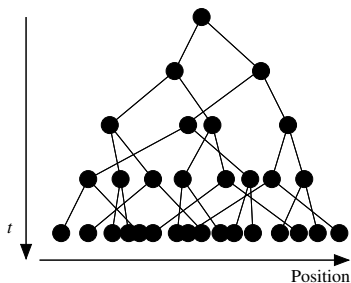
$$h(x, t+1) = \min \left[ 1, 2 \int_0^1 d\epsilon h(x-\epsilon, t) + \dots \right]$$

...

## 3 Fronts and Branching Brownian Motion



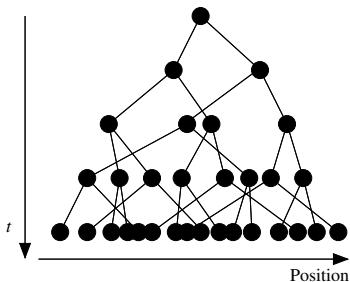
# The models



## Branching Random Walk

- At each **time step**, particles split into two
- The **positions** of the offspring are shifted by random **uncorrelated** amounts

# The models

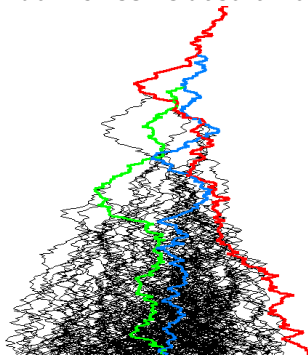


## Branching Random Walk

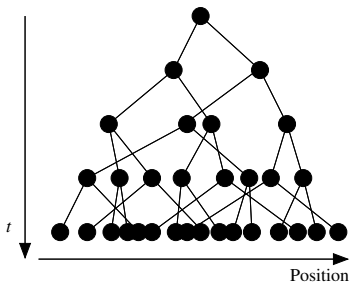
- At each **time step**, particles split into two
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## Branching Brownian Motion

- Particles do a Brownian motion
- With rate 1, they split



# The models



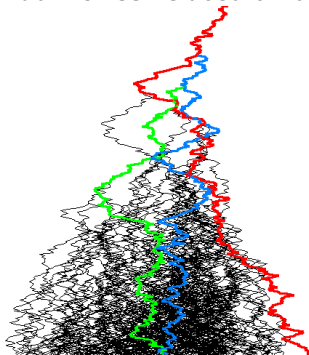
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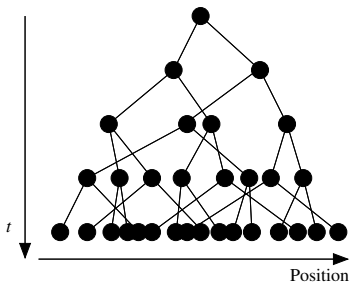
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**Also:** directed polymer on a Cayley tree, evolution, GREM (?)



# The models



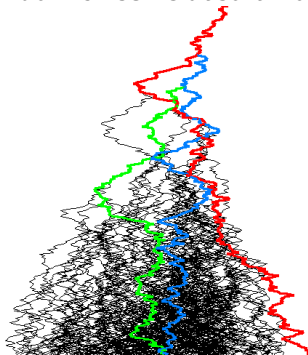
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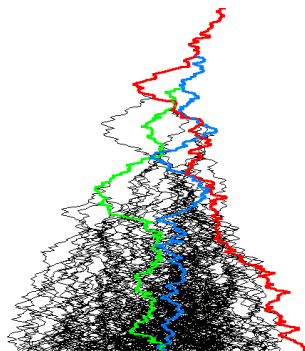


Positions of the rightmost particles ? (Energy spectrum ?)

# The rightmost particle

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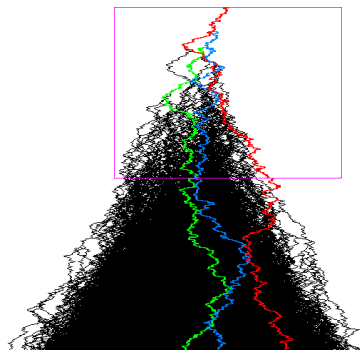




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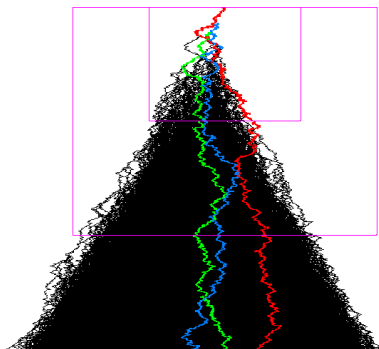
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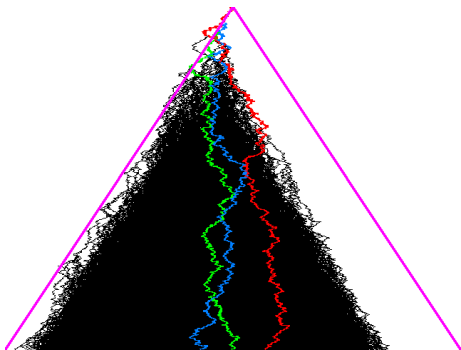
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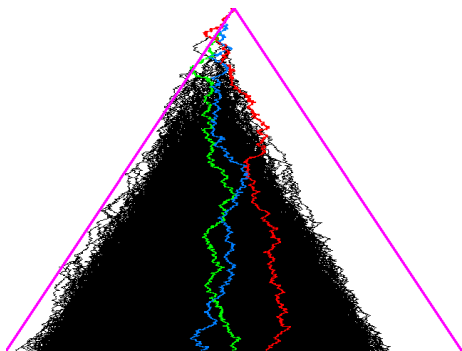
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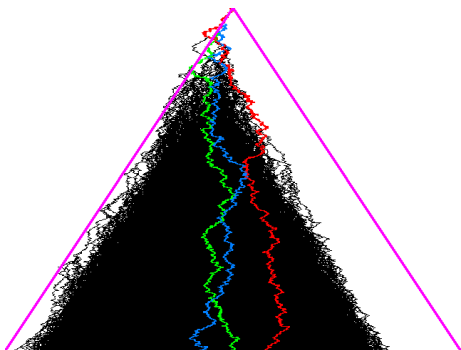
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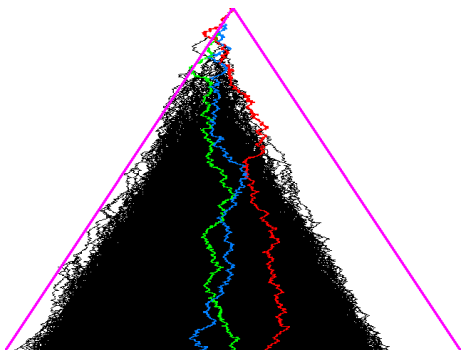
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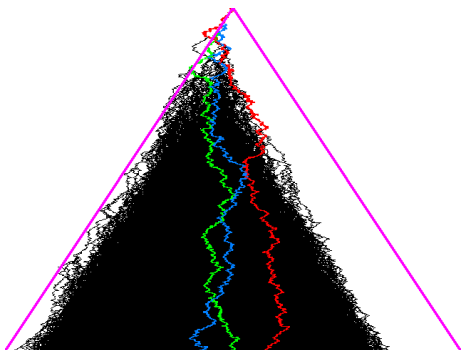
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**FKPP equation!** ( $h = 1 - Q$ )

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**FKPP equation!** ( $h = 1 - Q$ )

- Position of the rightmost

$$X_1(t) = 2t - \frac{3}{2} \ln t + \mathcal{O}(1)$$

## Why the FKPP equation ?

In general, for any well-behaved function  $\phi$ , let

$$H_\phi(x, t) = \left\langle \prod_i \phi[x - X_i(t)] \right\rangle$$



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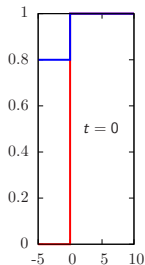
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# Position, shape and delay

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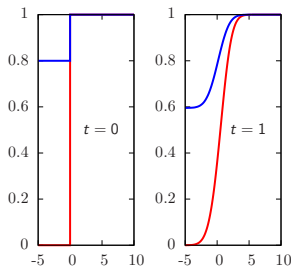
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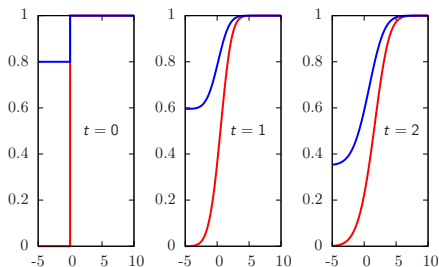
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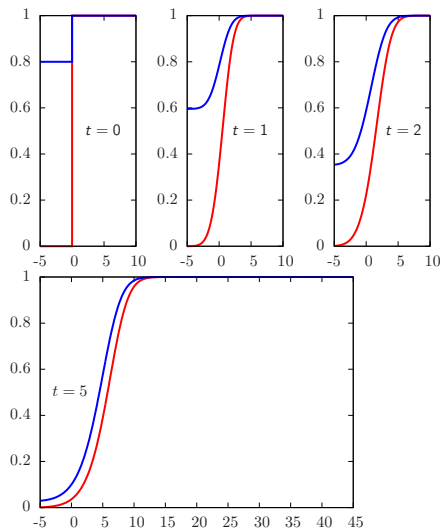
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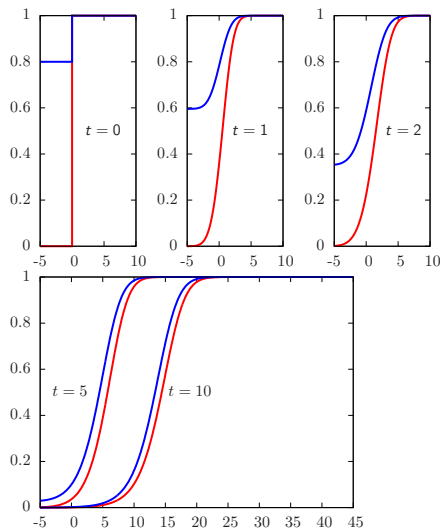
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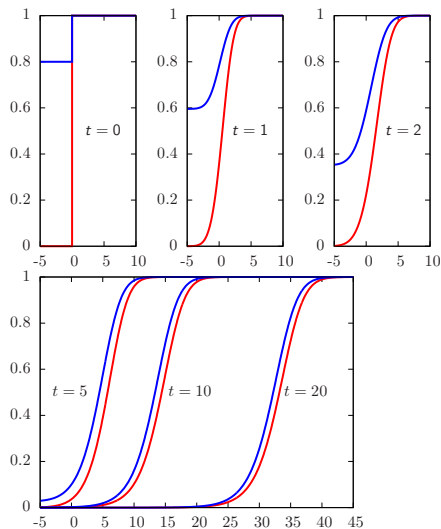
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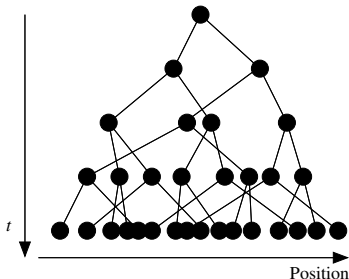


# Universality

$$H_\phi(x, t) = \left\langle \prod_i \phi[x - X_i(t)] \right\rangle$$

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- At each **time step**, particles split into two
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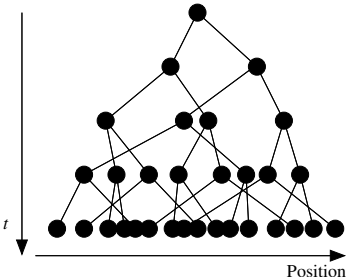
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Suppose  $\epsilon$  is uniform in  $[0, 1]$

$$H_\phi(x, t + 1) = \left[ \int_0^1 d\epsilon H_\phi(x - \epsilon, t) \right]^2$$

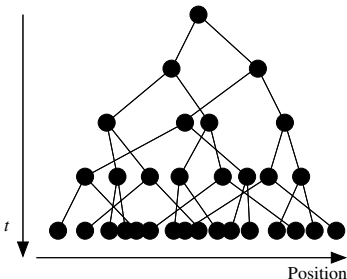
$$\nu = 0.815172\dots \quad \gamma = 5.26208\dots$$





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## Binary search tree

- During  $dt$ , a particle at position  $x$  is replaced with probability  $dt$  by two particles at position  $x + 1$

$$\partial_t H_\phi(x, t) = -H_\phi(x, t) + H_\phi(x - 1, t)^2$$

$$\nu = 4.31107\dots \quad \gamma = 0.768039\dots$$

## Average distances

$$H_\phi(x, t) = \left\langle \prod_i \phi[x - X_i(t)] \right\rangle$$





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$H_\phi$  gives the average positions of the rightmost particles

$$H_\phi(x, t) = \left\langle \lambda^{N(x, t)} \right\rangle \quad \text{with } N(x, t) = \left[ \begin{array}{l} \text{Number of particles on the} \\ \text{right of } x \text{ at time } t \end{array} \right]$$

$$H_\phi(x, t) = Q_0(x, t) + \lambda Q_1(x, t) + \lambda^2 Q_2(x, t) + \cdots$$

with  $Q_n(x, t)$  = proba to find  $n$  particles on the right of  $x$













# Average distances

## Summary

- ⇒  $H_\phi(x, t)$  obeys the FKPP equation
- ⇒ deduce the equations on  $Q_n(x, t)$
- ⇒ compute  $p_n(x, t)$
- ⇒ compute  $\langle X_n(t) \rangle$

$$\phi = \left( \begin{array}{c} \lambda \\ 0 \end{array} \left[ \begin{array}{c} \text{red step function} \\ \text{from } 0 \text{ to } 1 \end{array} \right] \right)$$

(proba  $n$  particles on the right of  $x$ )

(proba  $n^{\text{th}}$  rightmost particle at  $x$ )

(average position of  $n^{\text{th}}$  particle)







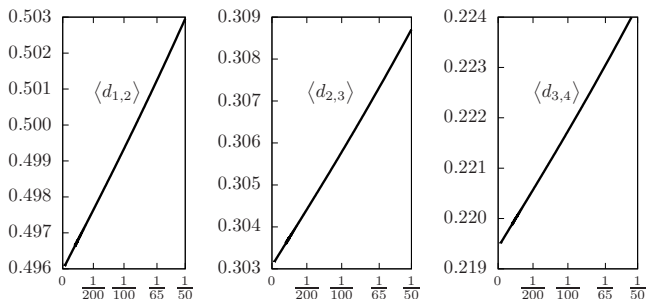






## Numerical results: average distances

The results: average distances as a function of  $1/t$



In the long time limit

$$\begin{aligned} \langle d_{1,2} \rangle_{st} &\simeq 0.496 & \langle d_{2,3} \rangle_{st} &\simeq 0.303 & \langle d_{3,4} \rangle_{st} &\simeq 0.219 \\ \langle d_{4,5} \rangle_{st} &\simeq 0.172 & \langle d_{5,6} \rangle_{st} &\simeq 0.142 & \langle d_{6,7} \rangle_{st} &\simeq 0.121 \end{aligned}$$

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## P.d.f. of the distances between two particles

$$H_\phi(x, t) = \left\langle \prod_i \phi[x - X_i(t)] \right\rangle \quad \text{with } \phi = \left( \begin{array}{c} \lambda\mu \\ 0 \end{array} \begin{array}{c} \lambda \\ -a \end{array} \begin{array}{c} 1 \\ 0 \end{array} \right)$$

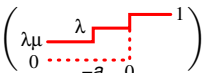
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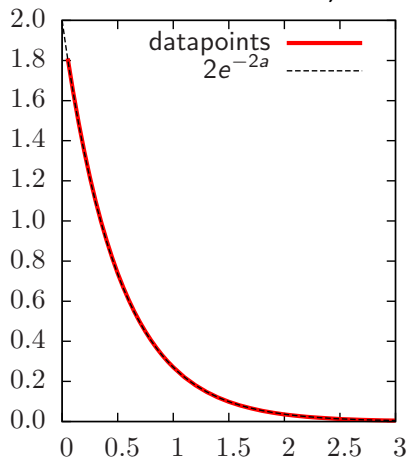
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$$\Rightarrow \int dx (\partial_x - \partial_a) R_{mn}(x, a, t) = \text{Proba} [X_m(t) - X_n(t) < a]$$

$H_\phi$  gives the p.d.f. of the distance between  $m^{\text{th}}$  and  $n^{\text{th}}$  particles

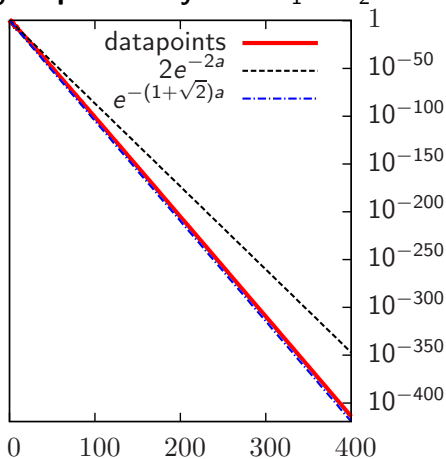
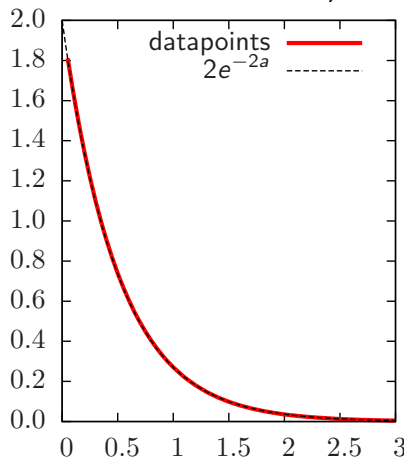
## Numerical results: p.d.f. of the distances

As of function of  $a$ , density of probability that  $X_1 - X_2 = a$



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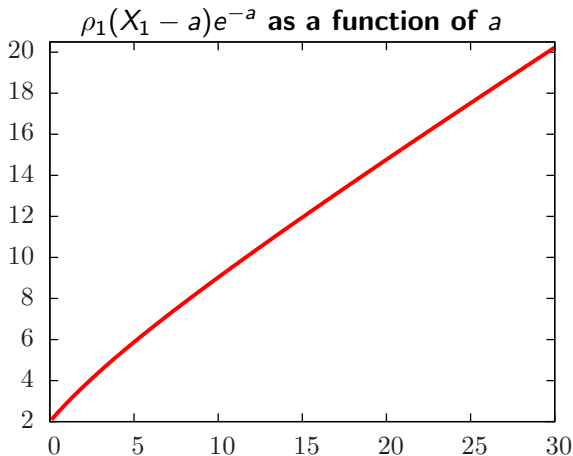
$$H_\phi(x, t) = \left\langle e^{-\lambda N(x-a, t)} \mathbb{1}_{N(x, t)=0} \right\rangle$$





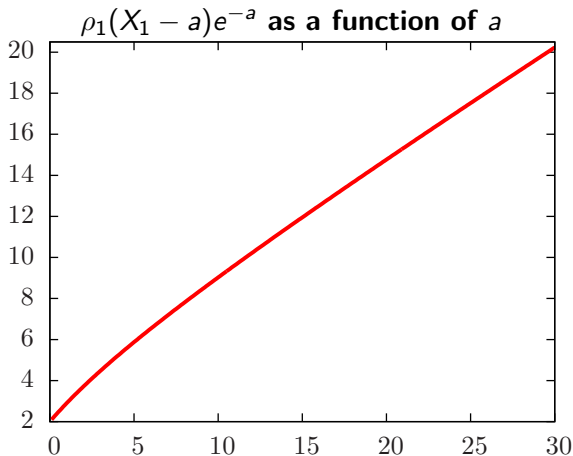


## Numerical results: density at a distance $a$



$$\rho_1(X_1 - a) = \frac{1}{da} \left( \begin{array}{l} \text{Average number of particles in an interval } da \\ \text{at a distance } a \text{ of the rightmost particle} \end{array} \right)$$

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$$\rho_1(X_1 - a) \simeq ae^a$$

## Analytical result: average distances

$$\partial_t H_\phi = \partial_x^2 H_\phi - H_\phi + H_\phi^2, \quad H_\phi(x, 0) = \phi(x)$$

$X_t$  is the position for  $\phi(x) = \left( \begin{array}{c} \text{red step function} \\ 0 \end{array} \right)$

$\tilde{X}_t$  is the position for  $\phi(x) = \left( \begin{array}{c} \text{red step function} \\ \text{dotted step function} \\ 0 \end{array} \right)$

$$\sum_{n \geq 1} \lambda^n \langle d_{n,n+1}(t) \rangle = X_t - \tilde{X}_t \xrightarrow[t \rightarrow \infty]{} \delta[\phi]$$

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$$\langle d_{n,n+1} \rangle_{\text{st}} = \frac{1}{n} - \frac{1}{n \ln n} + \dots$$

for large  $n$

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$$\partial_t H_\phi = \partial_x^2 H_\phi - H_\phi + H_\phi^2 \quad \text{with } H_\phi(x, 0) = \left( \begin{array}{c} \lambda \text{---} 1 \\ \text{---} 0 \\ \text{---} 0 \end{array} \right)$$

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- $\tilde{X}_t$  is the position, let  $v_t = \partial_t \tilde{X}_t$  be the velocity. For  $t$  large enough,  
 $H_\phi(x, t) \simeq F_{v_t}(x - \tilde{X}_t)$

$$\partial_x^2 F_v + v \partial_x F_v - F_v + F_v^2 = 0$$

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 $H_\phi(x, t) \simeq F_{v_t}(x - \tilde{X}_t) \simeq 1 - A_1(v_t) e^{-\gamma_t(x - \tilde{X}_t)}$

$$v_t = \gamma_t + \frac{1}{\gamma_t}, \quad \gamma_t < 1, \quad 1 - F_v(z) = A_1(v_t) e^{-\gamma_t z} + A_2(v_t) e^{-\frac{1}{\gamma_t} z}$$

## Analytical result: average distances

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- $\tilde{X}_t$  is the position, let  $v_t = \partial_t \tilde{X}_t$  be the velocity. For  $t$  large enough,  $H_\phi(x, t) \simeq F_{v_t}(x - \tilde{X}_t) \simeq 1 - A_1(v_t) e^{-\gamma_t(x - \tilde{X}_t)}$
- **Matching** in the range  $1 \ll x - \tilde{X}_t \ll \sqrt{t}$  gives the result
- As a bonus:  $\tilde{X}_t \approx 2t\sqrt{1 - \tau_\lambda/t}$ .

# Analytical result: average distances

$$\partial_t H_\phi = \partial_x^2 H_\phi - H_\phi + H_\phi^2$$

$$\text{with } H_\phi(x, 0) = \begin{cases} \lambda & x < 0 \\ 1 & x > 0 \end{cases}$$

For  $\lambda \simeq 1$ ,

- $\tau_\lambda =$  time needed

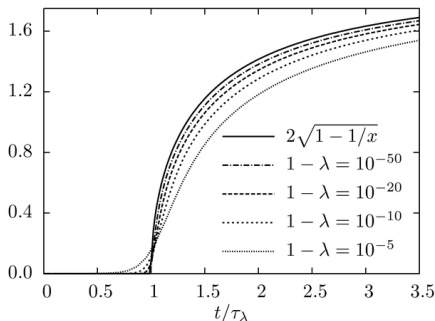
- As long as  $t \ll \frac{Y_t}{t}$

- $1 - H_\phi(x, t) \simeq$

- $\tilde{X}_t$  is the position where  $H_\phi(x, t) \simeq F_{v_i}$

- Matching in the range  $1 \ll x - \tilde{X}_t \ll \sqrt{t}$  gives the result

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$$= -\ln(1 - \lambda)$$

$x$  large enough

or  $t$  large enough,

## Analytical result: distance and density

P.d.f. of the distances:

$$\phi = \left( \begin{array}{c} \lambda \mu \\ \lambda \\ 0 \end{array} \begin{array}{c} \lambda \\ -a \\ 0 \end{array} \begin{array}{c} \text{step function} \\ \text{step function} \\ \text{step function} \end{array} \right) \implies Q_{mn}(x, a, t) \implies R_{mn}(x, a, t) \implies \dots$$

Number of particles on the right of  $X_1(t) - a$ :  $\phi = \left( \begin{array}{c} e^{-\lambda} \\ 0 \end{array} \begin{array}{c} 0 \\ a \end{array} \begin{array}{c} \text{step function} \\ \text{step function} \end{array} \right) \implies \dots$

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$$\partial_t Q = \partial_x^2 Q - Q + Q^2 \quad \text{with } Q(x, 0) = \left( \begin{array}{c} \text{step function} \\ 0 \end{array} \begin{array}{c} 0 \\ 0 \end{array} \begin{array}{c} 1 \\ 0 \end{array} \right)$$

$$\partial_t R_a = \partial_x^2 R_a - R_a + 2QR_a \quad \text{with } R_a(x, 0) = \delta(x + a) = \left( \begin{array}{c} \text{delta function} \\ -a \end{array} \begin{array}{c} 0 \\ 0 \end{array} \begin{array}{c} 1 \\ 0 \end{array} \right)$$

$$\partial_t \tilde{R}_a = \partial_x^2 \tilde{R}_a - \tilde{R}_a + 2Q\tilde{R}_a \quad \text{with } \tilde{R}_a(x, 0) = \delta(x - a) = \left( \begin{array}{c} \text{delta function} \\ 0 \end{array} \begin{array}{c} 0 \\ a \end{array} \begin{array}{c} 1 \\ 0 \end{array} \right)$$

## Analytical result: distance and density

P.d.f. of the distances:

$$\phi = \left( \begin{array}{c} \lambda \mu \\ 0 \end{array} \begin{array}{c} \lambda \\ -a \end{array} \begin{array}{c} \text{step function} \\ \text{from } -a \text{ to } 0 \end{array} \begin{array}{c} 1 \\ 0 \end{array} \right) \implies Q_{mn}(x, a, t) \implies R_{mn}(x, a, t) \implies \dots$$

$$\text{Number of particles on the right of } X_1(t) - a: \phi = \left( \begin{array}{c} e^{-\lambda} \\ 0 \end{array} \begin{array}{c} 0 \\ a \end{array} \begin{array}{c} \text{step function} \\ \text{from } 0 \text{ to } a \end{array} \begin{array}{c} 1 \\ 0 \end{array} \right) \implies \dots$$

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$$\text{Proba}[X_1(t) - X_2(t) > a] = \int dx R_a(x, t)$$
$$\langle N(X_1(t) - a, t) \rangle = \int dx \tilde{R}_a(x, t)$$



## Analytical result: distance and density

P.d.f. of the distances:

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$$\partial_t R_a = \partial_x^2 R_a - R_a + 2QR_a \quad \text{with } R_a(x, 0) = \delta(x + a) = \left( \begin{array}{c} \text{delta function} \\ \text{at } -a \end{array} \right)$$

$$\partial_t \tilde{R}_a = \partial_x^2 \tilde{R}_a - \tilde{R}_a + 2Q\tilde{R}_a \quad \text{with } \tilde{R}_a(x, 0) = \delta(x - a) = \left( \begin{array}{c} \text{delta function} \\ \text{at } a \end{array} \right)$$

$$\text{Proba}[X_1(t) - X_2(t) > a] = \int dx R_a(x, t) \approx e^{-(1+\sqrt{2})a} ?$$

$$\langle N(X_1(t) - a, t) \rangle = \int dx \tilde{R}_a(x, t) \approx ae^a ?$$

## Analytical result: distance and density

P.d.f. of the distances:

$$\phi = \left( \begin{array}{c} \lambda \mu \\ \lambda \\ 0 \end{array} \begin{array}{c} \text{step function} \\ \text{from } -a \text{ to } 0 \\ \text{height } 1 \end{array} \right) \implies Q_{mn}(x, a, t) \implies R_{mn}(x, a, t) \implies \dots$$

Number of particles on the right of  $X_1(t) - a$ :  $\phi = \left( \begin{array}{c} e^{-\lambda} \\ 0 \end{array} \begin{array}{c} \text{step function} \\ \text{from } 0 \text{ to } a \\ \text{height } 1 \end{array} \right) \implies \dots$

$$\partial_t Q = \partial_x^2 Q - Q + Q^2 \quad \text{with } Q(x, 0) = \left( \begin{array}{c} \text{step function} \\ \text{from } 0 \end{array} \right)$$

$$\partial_t R_a = \partial_x^2 R_a - R_a + 2QR_a \quad \text{with } R_a(x, 0) = \delta(x + a) = \left( \begin{array}{c} \text{delta function} \\ \text{at } -a \end{array} \right)$$

$$\partial_t \tilde{R}_a = \partial_x^2 \tilde{R}_a - \tilde{R}_a + 2Q\tilde{R}_a \quad \text{with } \tilde{R}_a(x, 0) = \delta(x - a) = \left( \begin{array}{c} \text{delta function} \\ \text{at } a \end{array} \right)$$

$$\text{Proba}[X_1(t) - X_2(t) > a] = \int dx R_a(x, t) \approx e^{-(1+\sqrt{2})a} ?$$

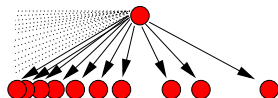
$$\langle N(X_1(t) - a, t) \rangle = \int dx \tilde{R}_a(x, t) \approx ae^a ?$$

$$R_a(x, t) \rightarrow \lambda_a Q'(x, t) \quad \text{for } t \text{ large}$$

Thank you !

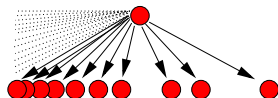
# Exponential model

- $N$  particles, discrete time
- Each particle has infinitely many offspring given by a Poisson process of density  $\psi$ : for each  $dx$ , there is an offspring with probability  $\psi(x - x_{\text{parent}}) dx$
- One only keep the  $N$  rightmost particles of a given generation



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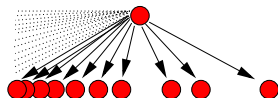


Usually a Fisher equation

$$v(\gamma) = \frac{1}{\gamma} \ln \left( \int d\epsilon \psi(\epsilon) e^{\gamma \epsilon} \right)$$

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But not always:  $\psi(\epsilon) = e^{-\epsilon}$

# Exponential model vs Fisher

	Exponential model	Fisher case
$v_N$	$\ln(\ln N + \ln \ln N) + \mathcal{O}\left(\frac{1}{\ln N}\right)$	$v^* - \frac{A}{(\ln N + 3 \ln \ln N)^2}$
$D_N$	$\frac{\pi^2}{3(\ln N + \ln \ln N)} + \mathcal{O}\left(\frac{1}{\ln^2 N}\right)$	$\frac{B}{(\ln N + ???)^3}$
$p(\delta)$	$e^{-\delta}$	$C_1 e^{-\gamma^* \delta}$
$R(\delta)$	$\ln\left(1 + \frac{e^\delta}{\ln N}\right)$	$\frac{1}{\gamma^*} \ln\left(1 + C_2 \frac{e^{\gamma^* \delta}}{\ln^3 N}\right)$
Relaxation time	1	$\ln^2 N$
Fluctuation size	$\ln \ln N$	$\frac{1}{\gamma^*} 3 \ln \ln N$

◀ Conclusion